

# SK計劃課程

## 114-2授課教師教學內容

- 課程時間目前可能安排於：  
3-CD、5-78

\*各教師課程內容規畫會另調整安排

- 114-2開課課程：個案研究、問題解決
- 115-1開課課程：個案研究、工業工程方法
- 115-2開課課程：個案研究、問題解決
- 116-1開課課程：個案研究、工業工程方法



# Case study: Ergonomics 個案研究: 人因工程

EMG



EEG



眼動儀 Eye-tracking



推拉力設備

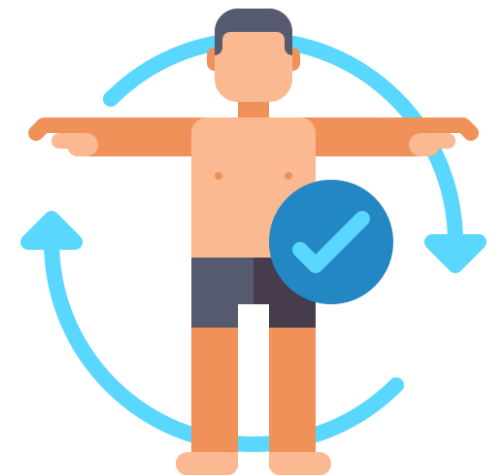


# Case study: Ergonomics

## 個案研究: 人因工程

1. Prerequisite: Motion and Time Study, Ergonomics
2. Course Design 依實際授課狀況 適時滾動式調整

No.	Content
1	Lecture: Introduction of course and ergonomics, introduce HW1
2	Oral presentation-HW1, Lecture: MSDs, introduce HW2
3	Oral presentation-HW2, Lecture: KIM, introduce HW3
4	Offline
5	Oral presentation of guided reading-HW3, introduce HW4
6	Offline: Prepare mid-term exam
7	Oral presentation of guided reading-HW4
8	Final project-topic
9	Conduct experiment
10	Conduct experiment
11	Data analysis
12	Discussion
13	Offline: Prepare final report of slide & hard-copy
14	Final presentation





# Case Study

(Service Quality and Crisis Management)



Case material is taken from Kung-Hwa  
Management Cases Collections

# Case Study

## (Service Quality and Crisis Management)

### Teaching Plan and Class Discussion:

1. Service Quality Perceived by Customers
2. Service Failure
4. Service Recovery
5. Crisis Management
6. Case study on Service Industry  
Aviation, Hospital, Hotel, Catering industry...



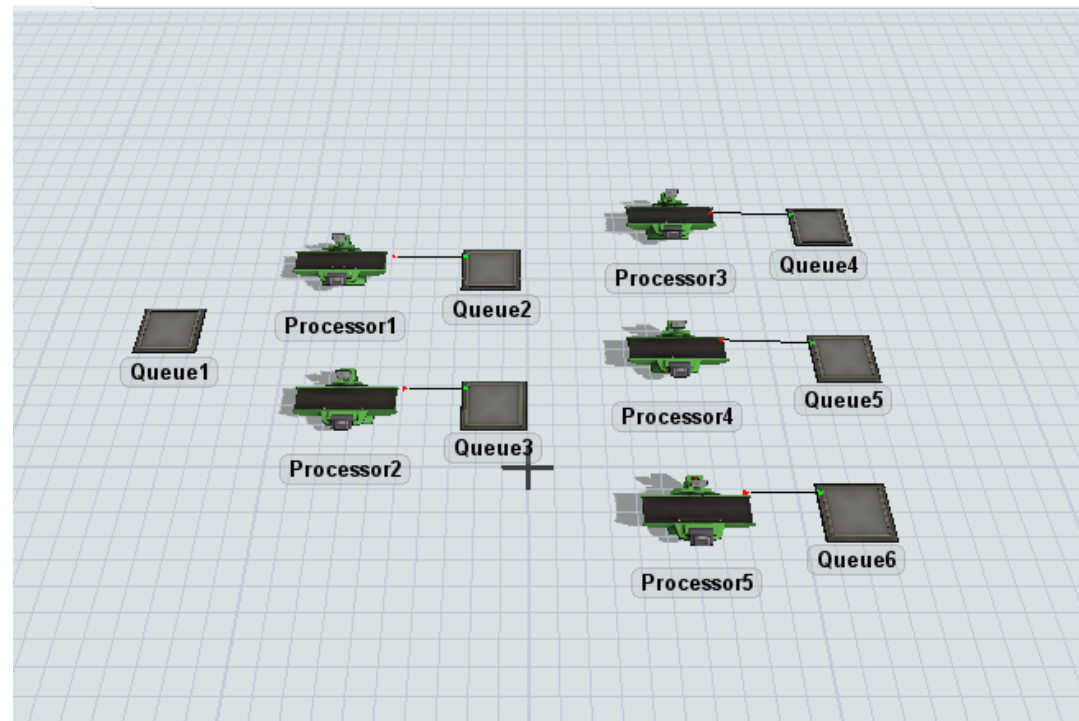
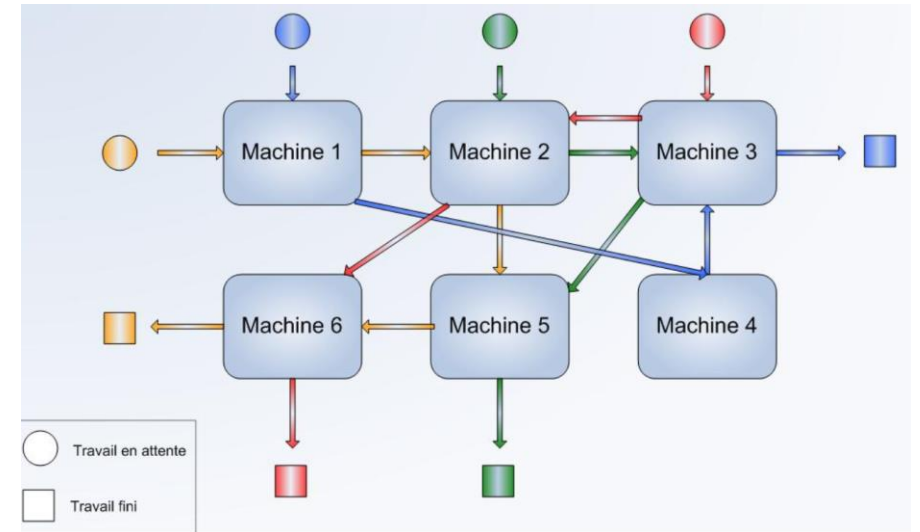
# Simulation – FlexSim and Witness

- Kendall notations and basic Statistics and Queueing Concepts 1 hour
- FlexSim Little Factory (2 hours)
  - Source, Sink, Queue, Processor
  - Conveyors, Stack, Transporter, AGV
  - Global Table, List
- Witness Little Factory (2 hours)
  - TBD
- FlexSim Healthcare Little model (4 hours)
  - Process Flow
  - People Module
- Case study
  - Student Group Project

- 3D Model
  - Queue × 6 – temporally place items

# Simple Jobshop System

- General Process flow
  - Source – Generate Token
  - Create Object – Generate item (product)
  - Sink – Destroy Token
- 3D Model
  - Queue × 6 – temporally place items
  - Processor × 5 – proceed items
- Tool Box
  - Item List
  - Global Table



	M1	M2
P1	1	3
P2	1	4
P3	1	5
P4	2	3
P5	2	4
P6	2	5

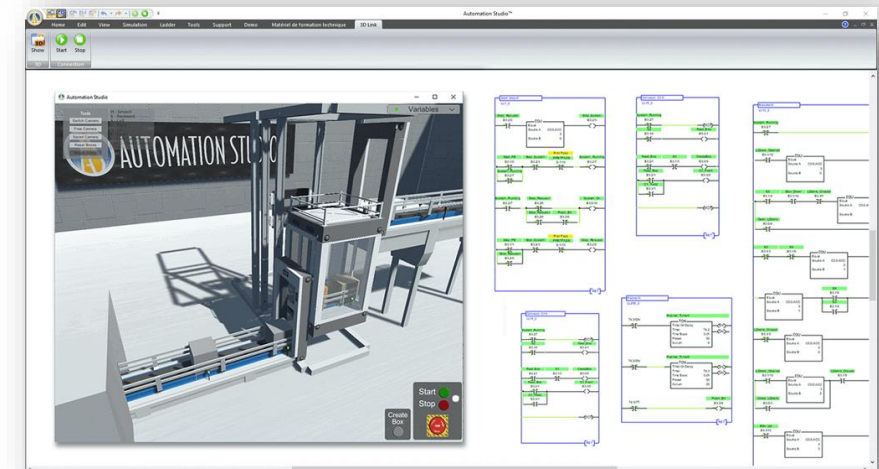
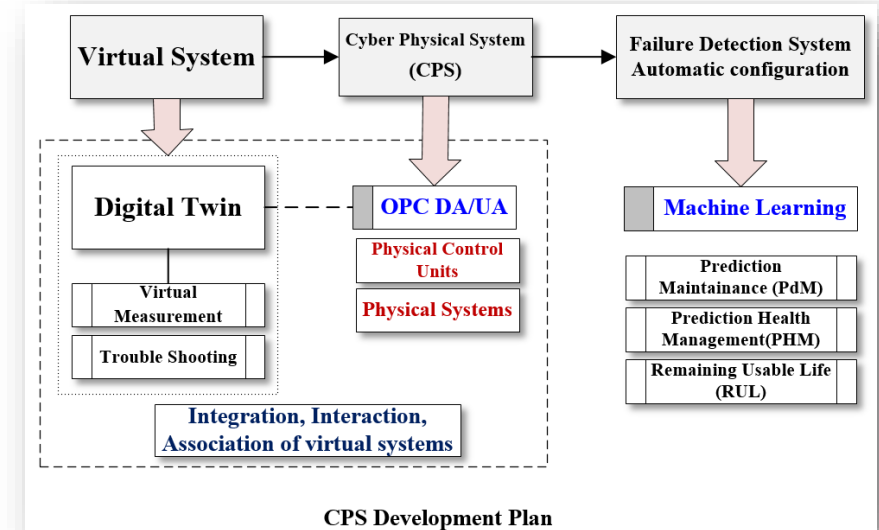
ProcessFlow ItemList1 Entries

Source  
+ Create Object  
Sink

# Manufacturing/AI : CPS introduction

- Phase 1: Virtual system development
  - Platform: Automation Studio
  - 1. Introduction of technologies applied to manufacturing systems
  - 2. Process control introduction
    - a) Actuators
    - b) Electric control system (JIC and IEC standards)
    - c) PLC and Ladder diagrams
    - d) Sequential Function Charts (SFC)
    - e) 3D virtual system development (Case study and existing equipment)

*Note: Please refer to the figures  
(1) CPS development Plan and  
(2) CPS development details*

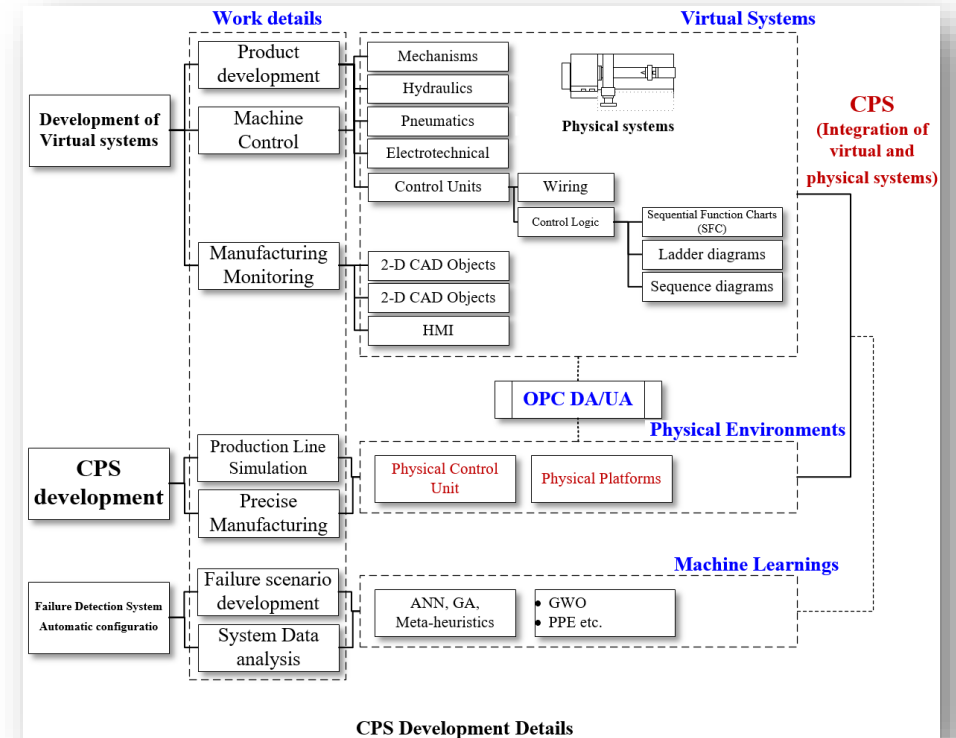




# Manufacturing/AI : CPS introduction

- Phase 2: CPS development
  - Platform: Automation Studio
  - 1. Introduction of physical control units
    - a) Mitsubishi
    - b) Omron
  - 2. Introduction of communication strategies
    - a) OPC servers
    - b) OPC DA/UA
    - c) Communications

*Note: Please refer to the figures  
(1) CPS development Plan and  
(2) CPS development details*



# AI Technology for Computer Vision Application(1/2)

## Object detection vs. image segmentation vs. image classification

Object detection



Image segmentation



Image classification



Source: <https://levity.ai/blog/what-is-an-image-classifier>

- Course Objectives
  - To learn the SOTA Object Detection and image segmentation method : YOLOv9

# AI Technology for Computer Vision Application(2/2)

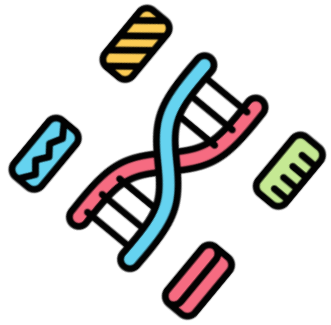
- Course Outline
  - What is Object Detection and Image Segmentation ?
  - Fundamentals of Convolutional Neural Network (CNN)
  - The Object Detection and Segmentation method : YOLOv9
  - The implementation of YOLOv9 using Pytorch library
    - » Train a YOLOv9 model using the image training dataset
    - » Inference the image testing dataset using your YOLOv9 model



AI real-time Field Crowd Surveillance Application



Industrial Safety Surveillance Application



# Metaheuristic Algorithm I

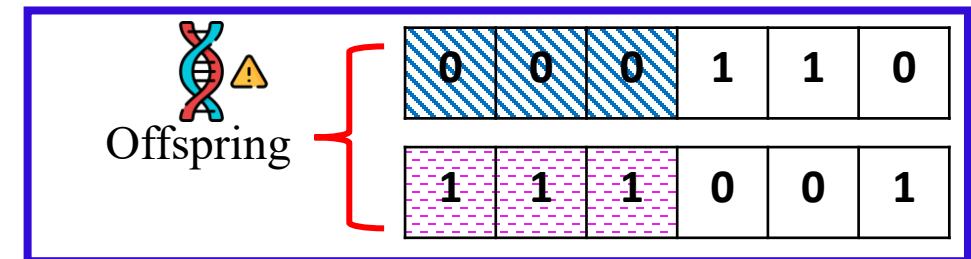
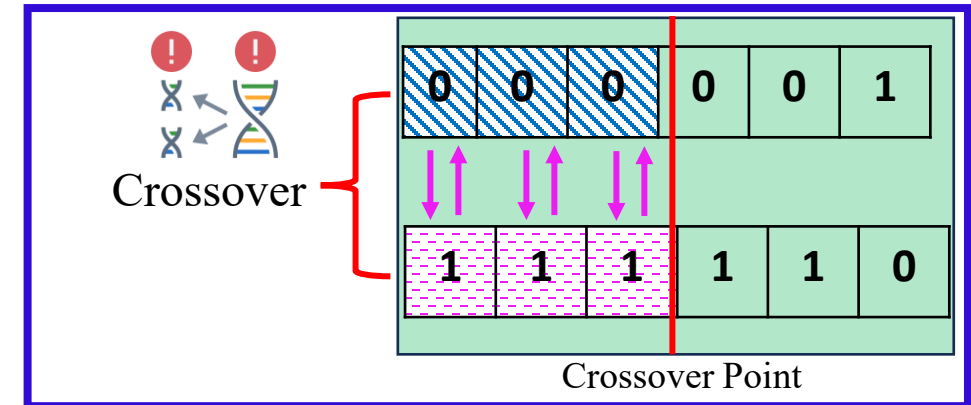
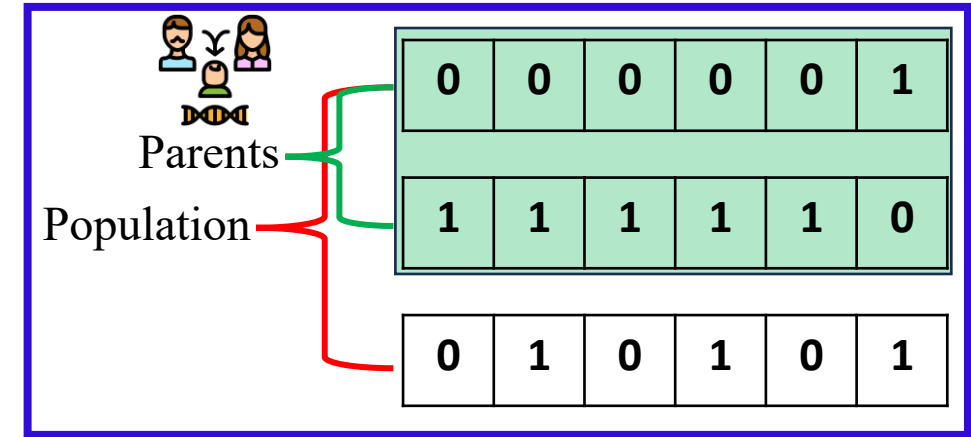
## Genetic Algorithm (GA)

This course will focus on the GA, a very common type of **Metaheuristic Algorithm**, which is suitable for situations where the best answer is sought among many choices.

※GA is applicable to many **Industrial Engineering** problems in **Management Science** and **Operations Research**.

Course Objectives: 

- ✓ Understand the basic concepts and operation principles of GA.
- ✓ Learn to design and implement simple GA to solve practical problems.
- ✓ Explore the practical applications of GA in management science and operations research.



## Metaheuristic Algorithm II

### Travelling salesman problem (TSP)

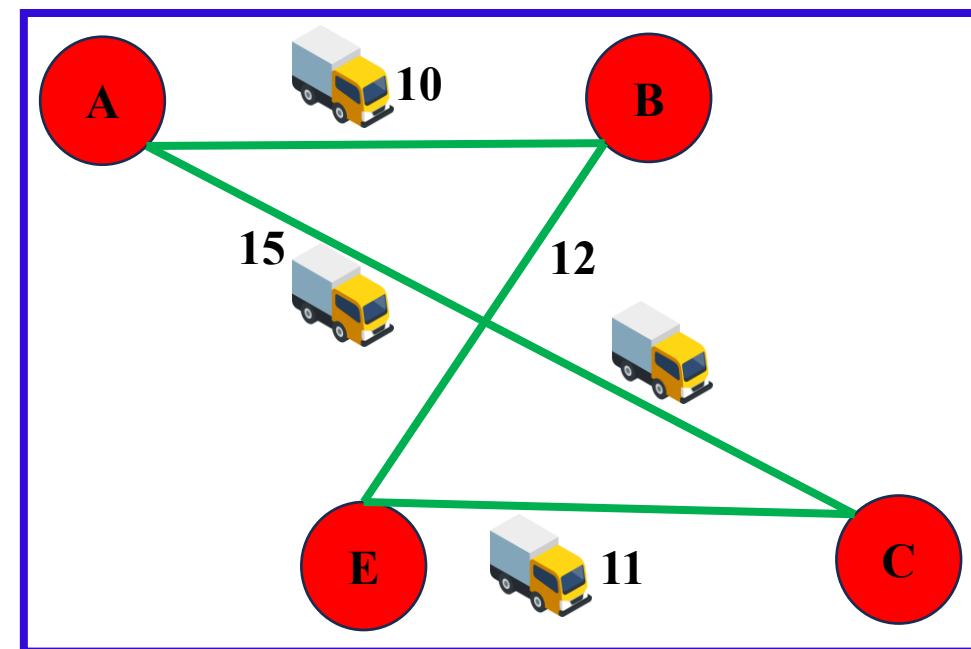
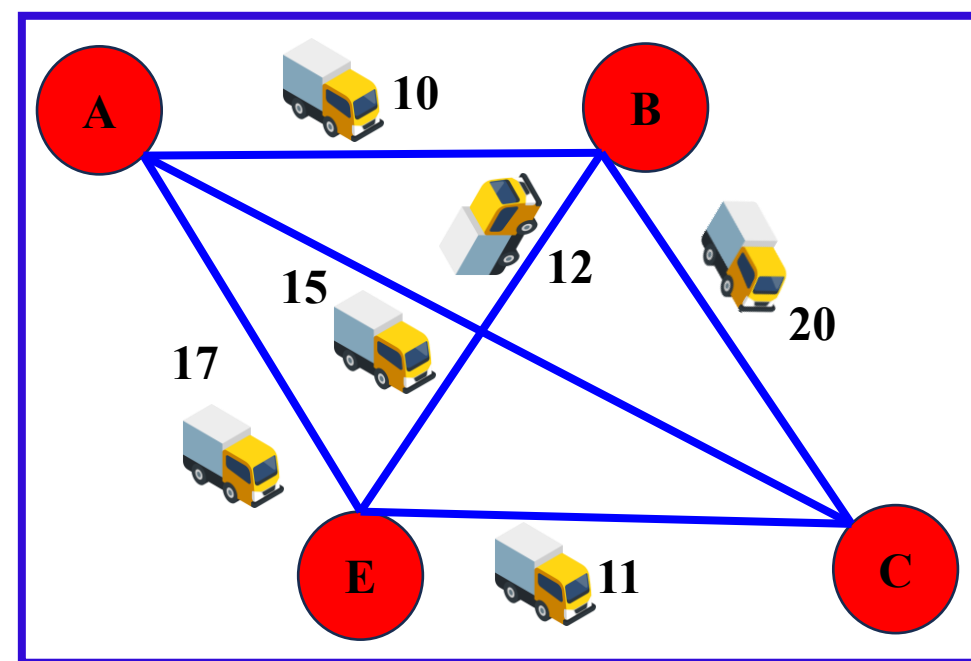
*The application of metaheuristic algorithm.*

The **Travelling Salesman Problem (TSP)** is a classic combinatorial **Optimization** problem.

- The goal is to find the shortest possible route that allows a salesman to visit each city exactly once and return to the starting city.
- TSP is widely used in **Logistics**, **Routing**, and **Scheduling** applications.

#### Course Objectives:

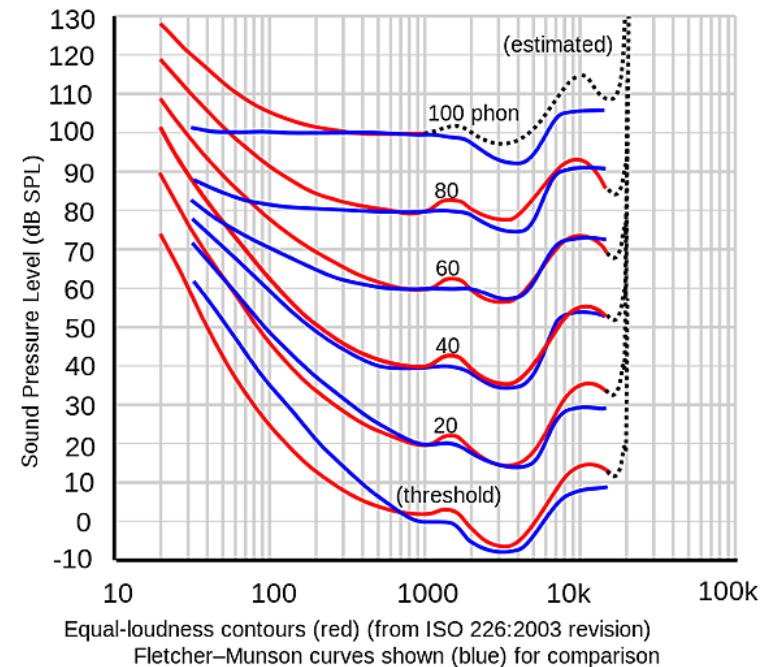
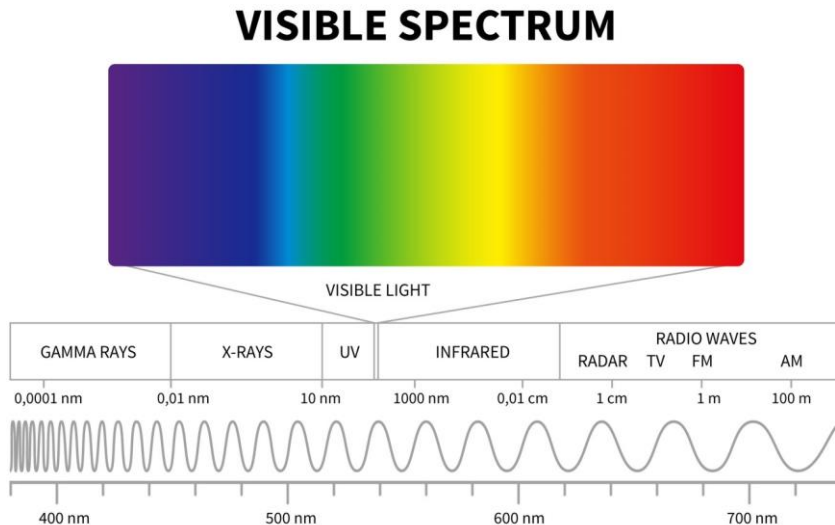
- ✓ Understand the definition and challenges of the TSP.
- ✓ Learn how to apply GA, PSO, and SA to solve the TSP and compare their effectiveness and characteristics.





# Human factors in lighting and sound

- Learn about lighting-related knowledge
- Understand the impact of lighting on user
- Learn about sound-related knowledge
- Understand the impact of sound on user



# Human factors in lighting and sound

- Through experiments, understand the interaction between humans and lighting environments.
- Using deep learning, model human behavior in lighting environments.
- Through experiments, understand the interaction between humans and sound environments.
- Using deep learning, model human behavior in sound environments.

$$\ln\left(\frac{P_H}{1-P_H}\right) = -10.847 + 0.189X_{WS} + 0.005X_{EN} - 0.146X_D$$

$$\ln\left(\frac{P_M}{1-P_M}\right) = -0.491 + 0.065X_{WS} - 0.079X_{EN} - 0.081X_D$$

$$\ln\left(\frac{P_L}{1-P_L}\right) = -0.995 + 0.051X_{WS} - 0.061X_{EN} - 0.063X_D$$

